

The fundamentals:

BIOMECHANICS and STABILITY of the SIJ & PELVIS

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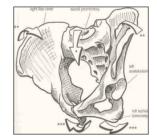
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Introduction to sacroiliac motion

- □ In order to discuss the mechanisms of pelvic stability one needs to begin with a study of the biomechanics
- □ The biomechanics are underpinned by the anatomy
- It has often been the study and discussion of the SIJ biomechanics that has generated much of the controversy surrounding SIJ or pelvic motion
- Much of the so-called research from the early & mid-20th century into SIJ biomechanics comes from clinical observation
- □ AND clinicians should be wary of hypotheses that have not been tested and verified experimentally

SIJ Biomechanics

- The physiological movements occurring at the SIJ are described in relation to either the sacrum or the innominate
- The main movements of the sacrum are:
- nutation and
- counternutation



Nutation and counternutation describe how the sacrum moves relative to the innominates

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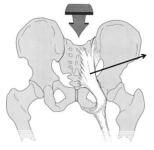
Biomechanics

■ Motion of the pelvis occurs in all 3 body planes:

- 1. Flexion/extension in the sagittal plane during forward and backward bending
- 2. Side flexion in the **coronal** plane during lateral bending and
- 3. Axial rotation in the **transverse** plane during twisting of the trunk
- A combination of all these motions occurs during the normal gait cycle and other habitual movements

Sacral nutation

- Bilateral sacral nutation occurs during the initial stages of forward bending of the trunk
- Unilateral sacral nutation occurs during flexion of the lower extremity



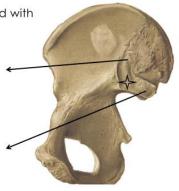
This motion is resisted by the interosseous and sacrotuberous ligaments

The primary SIJ axis

The SIJ is roughly L-shaped with 2 arms at 90°

 A short arm or vertical arm at the level of \$1

2. The longer arm or AP arm at \$2,3,4



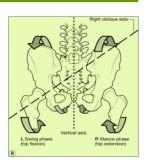
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The controversy: Multiple versus fixed axes of motion

- The number of potential axes for pelvic motion tends to confuse and complicate pelvic/sacral mechanics
- □ Mitchell et al (1979) describes 6-fixed axes:
- 1 axis through the pubic symphysis
- 3 transverse axes
- And right and left diagonal sacral axes
- The axes are dependent on whether the loading occurs from the spine (sacroiliac) or lower extremities (ilio-sacral)
- Helped name osteopathic SIJ dysfunctions

Controversy: An 'oblique axes' of motion

■ Magoun (1940) proposed that the sacrum rotates about an oblique axis running from the upper pole on one side to the lower pole on the opposite side



Postulated: a degree of sacral rotation/torsion needs to take place to explain for the complex nature of gait biomechanics

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Introducing PELVIC STABILITY

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The Pelvis

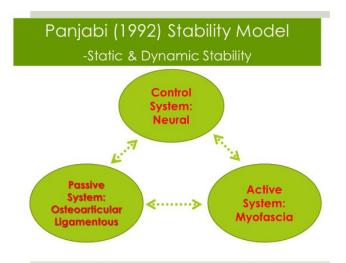
Fundamental point:

Primary function:

- ■The joints of the pelvis
- the pubic symphysis
- the sacroiliac joints

Must be able to absorb and transmit forces efficiently for optimal function



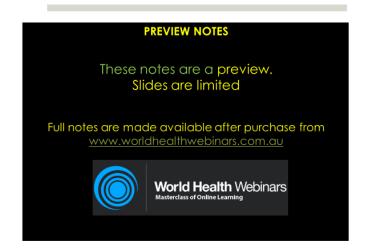


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So how does the SIJ maintain its stability within the pelvic girdle?

A model for pelvic stability

- A conceptual model has been proposed in which form and force closure are used to describe how:
- □Effective load is transferred through the pelvic girdle
- ■Snijders & Vleeming (1993)



What is form-force closure & why is it important to the pelvis?

SIJ Stability & function

Vertical shear in the SIJ is prevented by:

- The combination of the specific anatomical features of form closure
- And the compression generated by muscles and ligaments that can be accommodated to the specific loading situation of force closure

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Load transfer through the pelvic girdle is dynamic process

■Depends on a number of factors:

- Optimal function of bones, joints and ligaments to ensure joint congruency
- 2. Optimal function of the muscle and fascia
- 3. And appropriate neuromuscular control

Vleeming et al (1990a, 1990b, 1993)

Other points to consider: SIJ & the role in gait

The principal function of the SIJ's is:

■ To act as a stress reliever ensuring that the pelvic girdle is not a solid ring of bone that would crack under the stresses to which it is subjected

The SIJ's in humans serve a purpose:

□to economise gait

☐ to allow shock & shear absorption

Bogduk 1997, Adams et al 2002

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